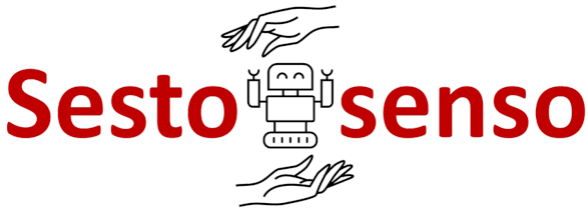


Physical Cognition for Intelligent Control and Safe Human-Robot Interaction



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